Progress on power spectrum extraction

Geraint Harker Kapteyn Institute

Motivation (I) Information from the power spectrum

$$\frac{\delta T_{\rm b}}{\rm mK} = 39h(1+\delta)x_{\rm HI} \left(1 - \frac{T_{\rm CMB}}{T_{\rm spin}}\right) \left(\frac{\Omega_{\rm b}}{0.042}\right) \left[\left(\frac{0.24}{\Omega_{\rm m}}\right) \left(\frac{1+z}{10}\right)\right]^{\frac{1}{2}}$$

- Measure the power spectrum of $\Delta \delta T_{\rm b}$, the difference of $\delta T_{\rm b}$ from the mean.
- Contains information on:
 - the growth of structure (through $1+\delta$);
 - reionization (through x), e.g. growth of bubbles;
 - heating (through dependence on the spin temperature);
 - cosmology;
 - redshift-space distortions.
- Decomposing P(k,μ) in powers of μ may help disentangle these effects.

Components of the data cubes



- Cosmological signal here from the f250C simulation of Iliev et al. (2008).
- Foregrounds and cosmological signal are convolved with the instrumental response.
- Uncorrelated noise in the *uv* plane: for one year with one beam, corresponds to an *rms* of 52mK at 150 MHz.
- Need foregrounds which are smooth as a function of frequency.

Wp smoothing: non-parametric foreground fitting

• Model data points (x_i, y_i) by:

$$y_i = f(x_i) + \varepsilon_i, \ i = 1, \dots, n$$

• Then we wish to solve the following problem:

$$\min_{f} \left\{ \sum_{i=1}^{n} \rho_i(y_i - f(x_i)) + \lambda R[f] \right\}$$

"Least squares" Roughness penalty

- Here the roughness penalty measures the integrated change in curvature 'apart from inflection points'; inflection points are the primary measure of roughness.
- The solution of this minimization is the solution of a boundary value problem derived by Mächler.
- 'Wp' stands for 'Wendepunkt'.

Motivation (II) Step 1: Measure the RMS?



- First aim: establish that we can detect any signal at all from the EoR.
- Seems reasonable to do this using the integrated RMS, which evolves with redshift.
- Unfortunately, polluted by under- and overfitting, and by edge effects.
- Can using scaledependence help?

Scale dependence and size of components of the signal



- Noise (receiver noise plus sky noise) dominates on small scales, leading to problems from over-fitting.
- Foregrounds dominate on larger scales, leading to problems from under-fitting.
- All scales contribute to the integrated RMS, but using the whole power spectrum we may be able to pick out the most favourable scales.
- Recovered shape provides a further check.

Motivation (III): using the power spectrum to recover the skewness



 Recovery seems to be robust to changes in the fitting algorithm.

- Redshift evolution of the skewness of residual maps may provide a confirmation of a detection (especially if we see negative skewness).
- Need to deconvolve the maps (e.g. Wiener deconvolution) before calculating the skewness, which requires an estimate of the correlation matrix (and hence angular power spectrum) of the signal.



- Spectra here are convolved with the instrumental response (hence high-k cut-off).
- Growth of a feature on small scales due to formation of bubbles.
- Feature broadens and moves to larger scales as bubbles grow.
- At low redshift, signal drops because of a low neutral fraction.



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Power spectra with perfect foreground subtraction (1 year, 1 beam)

High redshift

Power spectra with perfect foreground subtraction (1 year, 4 beams)

Low redshift

High redshift

Power spectra with perfect foreground subtraction (4 years, 4 beams)

Low redshift

High redshift

Results using Wp smoothing for foreground subtraction (1 yr, 1 beam)

High redshift

Results using Wp smoothing for foreground subtraction (1 yr, 4 beams)

Results using Wp smoothing for foreground subtraction (4 yr, 4 beams)

1D and 2D power spectra

2D power spectrum – low z,

1D power spectrum – high z, 1 yr, 1 beam

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0

20

-0.2

Redshift-dependent uv coverage

- The uv coverage changes as a function of redshift: high v increases the maximum k, moves holes across the uv plane and contracts 'frizz' from the PSF across unresolved point sources in the image plane.
- The latter effect introduces spurious small-scale power if we fit the foregrounds in the image plane.
- The most drastic solution is to throw away data until the *uv* coverage is the same at all frequencies.

Fitting in the uv plane

Comments and conclusions

- The power spectrum is a rich source of physical information.
- The different scale-dependence of the foregrounds, noise and cosmological signal may help in extracting the signal.
- Only a rough estimate of the power spectrum is required to extract the evolution of the skewness (after Wiener filtering).
- Foreground fitting is unlikely to be a bottleneck in extraction: we can afford something sophisticated even if it's computationally expensive.
- Realistic levels of noise and diffuse foregrounds do not, in themselves, seem to be a deal-breaker for power spectrum subtraction...
- ...but the fitting process introduces biases: can they be corrected for using simulation results?
- As the integration time increases, we can expect continued qualitative improvements in what can be inferred from the data.
- The effects of variable *uv* coverage seem to be manageable with a carefully chosen fitting scheme.

Future work

- How accurately can we really estimate the power spectrum of the noise? Probably need to use the data before they're binned in time and frequency to give a final data cube.
- How is the 'separation of powers' (of μ) affected by the fitting and extraction process?
- Continue to integrate improved models of the instrument, foregrounds, noise and a variety of signal models incorporating larger scales.
- Effect of other error sources: ionosphere, polarization calibration, point source subtraction errors...
- Incorporate signal correlations and a systematic way of choosing the amount of smoothing in the foreground fitting.
- Can we gain from mismatched spatial and frequency resolution?
- Effect of power spectrum errors on recovery of evolution of skewness.
- Full error analysis including cosmic variance; effect of multiple windows.